

Lorenzo Stella

Email lorenzostella@gmail.com
Web lostella.github.io
GitHub github.com/lostella

Professional experience

- Since 10/2017 | Applied Scientist at Amazon, Amazon Development Center, Berlin (Germany).
2011 – 2012 | Research Analyst at COSBI, Trento (Italy).
Analysis and simulation of stochastic models in systems biology (PK/PD, metabolic, gene regulatory networks). Collaboration with researchers and software developers to implement tools for the stochastic simulation of biological systems ([link](#)).

Education

- 2013 – 2017 | PhD in Computer, Decision and Systems Science, IMT Lucca (Italy), jointly with Department of Electrical Engineering (ESAT), KU Leuven (Belgium).
Supervisors: [Panos Patrinos](#) (KU Leuven), [Alberto Bemporad](#) (IMT Lucca). Algorithms for large-scale nonsmooth optimization problems, with applications to optimal control, distributed optimization, machine learning, image processing, recommender systems.
2004 – 2011 | BSc & MSc in Computer Science, University of Florence (Italy). Thesis advisor: [Luigi Brugnano](#).

Publications

- 2018 | L. Stella, A. Themelis, and P. Patrinos. Newton-type alternating minimization algorithm for convex optimization. *IEEE Transactions on Automatic Control*, September 2018. Online: [link](#)
A. Themelis, L. Stella, and P. Patrinos. Forward-backward envelope for the sum of two non-convex functions: Further properties and nonmonotone line-search algorithms. *SIAM Journal on Optimization*, 28(3):2274–2303, 2018. Online: [link](#)
2017 | L. Stella, A. Themelis, and P. Patrinos. Forward-backward quasi-Newton methods for nonsmooth optimization problems. *Computational Optimization and Applications*, 67(3):443–487, 2017. Online: [link](#)
L. Stella, A. Themelis, P. Sopasakis, and P. Patrinos. A simple and efficient algorithm for nonlinear model predictive control. In *56th IEEE Conference on Decision and Control (CDC)*, December 2017. Online: [link](#)
2016 | P. Latafat, L. Stella, and P. Patrinos. New primal-dual proximal algorithm for distributed optimization. In *55th IEEE Conference on Decision and Control (CDC)*, pages 1959–1964, December 2016. Online: [link](#)
2014 | P. Patrinos, L. Stella, and A. Bemporad. Douglas-Rachford splitting: Complexity estimates and accelerated variants. In *53rd IEEE Conference on Decision and Control (CDC)*, pages 4234–4239, December 2014. Online: [link](#)
P. Patrinos, L. Stella, and A. Bemporad. Forward-backward truncated Newton methods for convex composite optimization. *ArXiv e-prints*, February 2014. Online: [link](#)

Programming skills

- MATLAB | I worked with MATLAB since my BSc and used it on a daily basis during my PhD to implement [optimization algorithms](#) and perform numerical simulations.

JULIA	I learned JULIA in the Summer 2016 and used it ever since. I contribute to the package ecosystem, and intend to keep working with JULIA as I generally prefer it over MATLAB.
PYTHON	I am fully proficient with the language and popular scientific and machine learning libraries such as NumPy, Pandas, Scikit-learn, MXNet.
C	I am fully proficient with the language and often use it to implement efficient routines when this is not possible with high-level languages, like in this case .

Software projects

Proximal Operators.jl	<p>JULIA package to compute the proximal operator of several functions commonly used in optimization. The purpose is to have a toolbox of efficiently implemented operators, to be used as building blocks for large scale, nonsmooth optimization algorithms such as (fast) proximal gradient methods, ADMM, and primal-dual splitting algorithms.</p> <p>Web page: github.com/kul-forbes/ProximalOperators.jl</p>
Proximal Algorithms.jl	<p>Generic, efficient JULIA implementations of proximal algorithms for nonsmooth optimization problems, based on the first-order primitives provided by ProximalOperators.jl.</p> <p>Web page: github.com/kul-forbes/ProximalAlgorithms.jl</p>
ForBES	<p>MATLAB framework to develop solvers for nonsmooth optimization, contains a library of mathematical functions to formulate problems arising in control, machine learning, image and signal processing. Contains novel, efficient, Newton-type algorithms for nonsmooth problems based on my PhD research.</p> <p>Web page: kul-forbes.github.io/ForBES</p>

Languages

Native	English, Italian
Elementary	German (A2 level)